

Divergence-preserving unfitted FEM for the mixed Poisson problem

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MS50 - Mixed-Dimensional and Immersed Problems:
Numerical Discretization, Analysis and Applications.

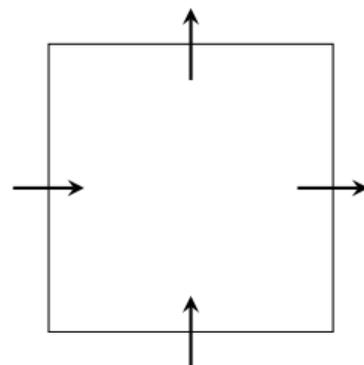
■ C.L., T.v.B., I.V., *Analysis of div.-preserving unfitted FEM for the mixed Poisson problem.*
Math. Comp., 2025.

- ▶ physical principles, e.g. conservation of mass:

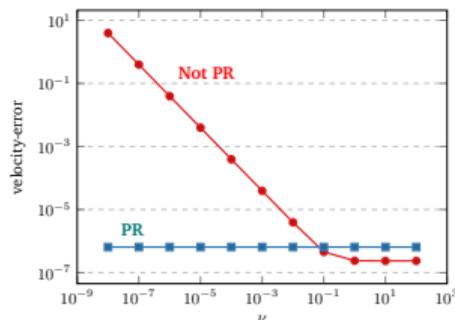
$$\text{continuity eq.: } \partial_t \rho + \operatorname{div}(\rho u) = 0$$

$$\rho \text{ const.: } \operatorname{div} u = 0$$

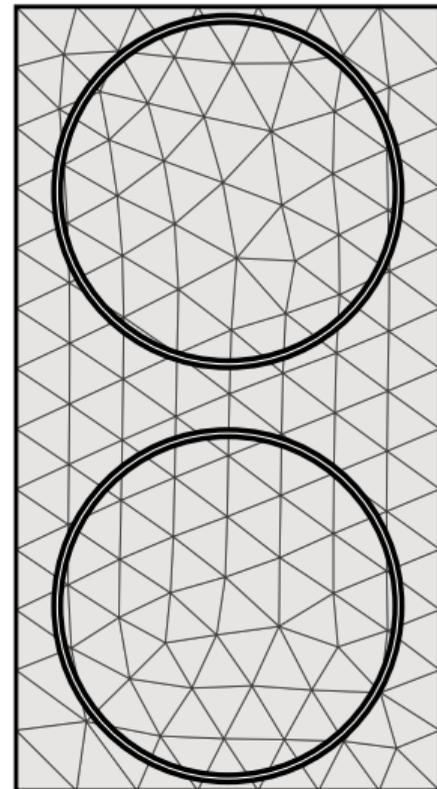
- ▶ desirable to transfer this to the discrete level, e.g. for *pressure robustness* of the Stokes problem
- ▶ How to obtain **divergence-preservation** in an **unfitted** setting?



$$f = -\nu \Delta u + \nabla p$$



- ▶ How to handle complicated (moving) geometries, possibly with topology changes?
- ▶ Unfitted FEM / Cut FEM / XFEM / Immersed FEM: separate the **geometry description** from the **computational domain**
- ▶ Challenges:
 - ▶ Imposition of boundary conditions
 - ▶ Numerical integration (robustness / high order?)
 - ▶ **Stability w.r.t. small cuts**



📖 E. Burman, P. Hansbo, M. G. Larson, S. Zahedi, *Cut finite element methods*. Acta Numerica, 2025.

📖 C. Lehrenfeld, M. A. Olshanskii, *An Eulerian FEM for PDEs in time-dependent domains*. ESAIM: M2AN, 2019.

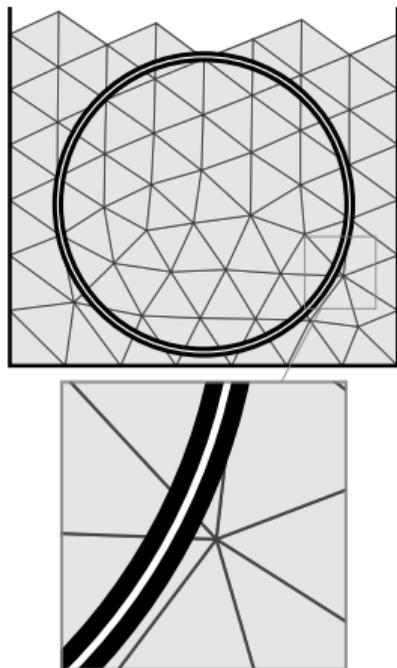
- ▶ need to obtain stability with respect to small cuts
- ▶ Remedy: ghost penalty stabilization

$$\mathfrak{G}(u_h, v_h) := \sum_{F \in \mathcal{F}_h^{\partial\Omega}} \sum_{l=0}^k \frac{h_F^{2l+1}}{l!^2} \int_F [[\partial_n^l u_h]] [[\partial_n^l v_h]] ds$$

- ▶ Grants stability through: $\|u\|_{H^q(\Omega)} + |u|_{\mathfrak{G}} \simeq \|u\|_{H^q(\Omega\mathcal{T})}$

📖 E. Burman, *Ghost penalty*. C.R. Math., 2010.

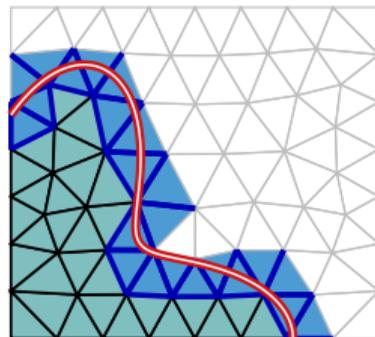
📖 J. Preuss, *Higher order unfitted isoparametric space-time FEM on moving domains*. 2018.



Model problem: Mixed Poisson / Darcy

Find u, p with $p = p_D$ on $\partial\Omega$ such that

$$\begin{aligned} u - \nabla p &= 0 \text{ in } \Omega, \\ \operatorname{div} u &= -f \text{ in } \Omega. \end{aligned}$$



- ▶ $T \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma$
- ▶ $T \in \mathcal{T}_h^\Gamma$
- = $\Gamma = \partial\Omega$
- ▶ \cup ▶ $= \Omega^T$

Naive variational formulation (unfitted)

Find $u_h \in \Sigma_h = \mathbb{RT}^k(\mathcal{T}_h) \subset H(\operatorname{div}, \Omega^T)$ and $p_h \in Q_h = \mathbb{P}^k(\mathcal{T}_h) \subset L^2(\Omega^T)$ s.t.

$$\begin{aligned} (u_h, v_h)_{L^2(\Omega)} + \text{👻} + (\operatorname{div} v_h, p_h)_{L^2(\Omega)} + \text{👻} &= (v_h, p_D)_{L^2(\partial\Omega)} & \forall v_h \in \Sigma_h, \\ (\operatorname{div} u_h, q_h)_{L^2(\Omega)} + \text{👻} &= (-f, q_h)_{L^2(\Omega)} & \forall q_h \in Q_h. \end{aligned}$$

→ Stable, but **mass balance is polluted** by 👻

Stab. Cons. HO.

- | | | | |
|---|---|---|--|
| ● | ○ | ● | R. Puppi, <i>A cut FEM for the Darcy problem</i> . arXiv, 2021. |
| ● | ○ | ● | P. Cao, J. Chen, <i>An extended FEM for coupled Darcy-Stokes problems</i> . IJNME, 2022. |
| ● | ● | ● | T. Frachon, P. Hansbo, E. Nilsson, S. Zahedi, <i>A Divergence Preserving Cut FEM for Darcy Flow</i> . SISC, 2024. |
| ● | ● | ● | T. Frachon, E. Nilsson, S. Zahedi, <i>Divergence-free cut FEMs for Stokes flow</i> . BIT, 2024. |
| ● | ● | ○ | E. Burman, P. Hansbo, M. G. Larson, <i>Cut FEM for Divergence-Free Approx. of Incompr. Flow: A Lagrange Multiplier Approach</i> . SINUM., 2024. |
| ● | ● | ● | C. Lehrenfeld, TvB, I. Voulis, <i>Analysis of div.-preserving unfitted FEM for the mixed poisson problem</i> . Math. Comp., 2025. |

Stability of saddle point problem

Set $a(u_h, v_h) := (u_h, v_h)_{L^2(\Omega)}$ and $b(v_h, p_h) = (\operatorname{div} v_h, p_h)_{L^2(\Omega)}$.

- ▶ **Kernel coercivity** of $a(\cdot, \cdot)$:

$$a(u_h, u_h) \geq \alpha \|u_h\|_{\Sigma_h}^2 \quad \forall u_h \in \Sigma_h \cap \ker B_h$$

- ▶ **Inf-sup stability** of $b(\cdot, \cdot)$:

$$\inf_{q_h \in Q_h} \sup_{v_h \in \Sigma_h} \frac{|b(v_h, q_h)|}{\|v_h\|_{\Sigma_h} \|q_h\|_{Q_h}} \geq \gamma > 0.$$

$$\begin{pmatrix} A & B^T \\ B & 0 \end{pmatrix} \begin{matrix} \curvearrowright \\ \curvearrowleft \end{matrix}$$

$$\begin{pmatrix} A_h & B_h^T \\ B_h & 0 \end{pmatrix}$$

→ Modify $b(\cdot, \cdot)$ without changing its kernel?

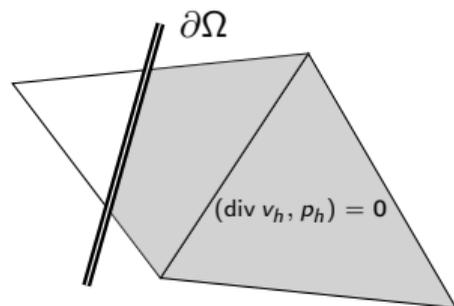
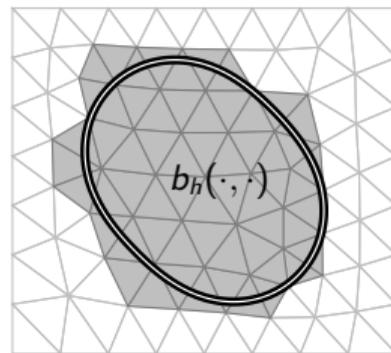
Goal: Modify $b(v_h, p_h) = (\operatorname{div} v_h, p_h)_{L^2(\Omega)}$ to obtain stability without polluting the mass balance

- ▶ Extend domain^{1,2} of $b(\cdot, \cdot)$: $\Omega \rightsquigarrow \Omega^{\mathcal{T}}$

$$b_h(v_h, p_h) := (\operatorname{div} v_h, p_h)_{\Omega^{\mathcal{T}}} \\ \Rightarrow \ker b_h = \ker b$$

- ▶ Modify $\gamma_{\Omega}(\cdot, \cdot)^3$:

$$b_h(v_h, p_h) = (\operatorname{div} v_h, p_h)_{L^2(\Omega)} + \gamma_{\Omega}(\operatorname{div} v_h, p_h)$$



- 1. Burman, Hansbo, Larson, 2024; 2. Lehrenfeld, vB, Voulis, 2025
- 3. Frachon, Nilsson, Zahedi, 2024

Stable unfitted mixed Poisson

With $\gamma_{\text{👤}} \geq 0$, find $u_h \in \Sigma_h = \mathbb{RT}^k(\mathcal{T}_h)$ and $\bar{p}_h \in Q_h = \mathbb{P}^k(\mathcal{T}_h)$ such that

$$\begin{aligned} a_h(u_h, v_h) + b_h(v_h, \bar{p}_h) &= (v_h \cdot n, p_D)_{L^2(\partial\Omega)} & \forall v_h \in \Sigma_h, \\ b_h(u_h, q_h) &= -(f_h, q_h)_{L^2(\Omega\mathcal{T})} & \forall q_h \in Q_h, \end{aligned} \quad (1)$$

with the bilinear forms

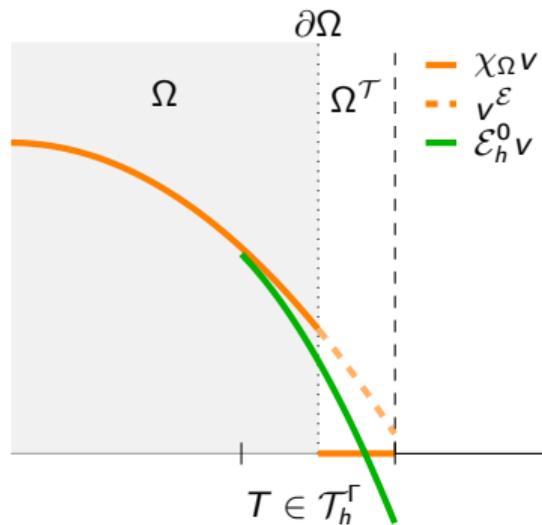
$$a_h(u_h, v_h) := a(u_h, v_h) + \gamma_{\text{👤}}(u_h, v_h); \quad b_h(v_h, p_h) := (\operatorname{div} v_h, p_h)_{L^2(\Omega\mathcal{T})}.$$

- ▶ f_h is a suitable discrete extension of f from Ω to $\Omega^{\mathcal{T}}$ (Assump.: approx. $f^{\mathcal{E}}$ well)
- ▶ (1) is **stable** (independent of cut position), u_h consistent with u (up to $f_h \approx f$)
- ▶ Mass balance is preserved

- ▶ $\bar{p}_h \approx p$ on $T \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma$, but $\bar{p}_h \not\approx p$ on cut elements $T \in \mathcal{T}_h^\Gamma$
- ▶ Define $\mathcal{E}_h^0 : L^2(\Omega) \rightarrow Q_h$, $v \mapsto \Pi_{Q_h}(\chi_\Omega \cdot v)$ s.t.

$$(\mathcal{E}_h^0 q, r_h)_{L^2(\Omega^\mathcal{T})} = (\chi_\Omega \cdot q, r_h)_\Omega \quad \forall r_h \in Q_h,$$

- \mathcal{E}_h^0 is the $L^2(\Omega^\mathcal{T})$ -projection into Q_h of the extension by zero



Interpretation of \bar{p}_h

It holds $b(v_h, q) = (\operatorname{div} v_h, q)_{L^2(\Omega)} = (\operatorname{div} v_h, \mathcal{E}_h^0 q)_{\Omega^\mathcal{T}} = b_h(v_h, \mathcal{E}_h^0 q)$ and thus

$$\bar{p}_h \approx \mathcal{E}_h^0 p.$$

Norm on $H(\text{div}, \Omega^T)$:

$$\|u\|_{\Sigma}^2 := \|\text{div } u\|_{\Omega^T}^2 + \|u\|_{\Omega_\gamma}^2, \quad \|u\|_{\Omega_\gamma}^2 := \begin{cases} \|u\|_{L^2(\Omega^T)}^2 & \text{if } \gamma_{\text{red}} > 0, \\ \|u\|_{L^2(\Omega)}^2 & \text{if } \gamma_{\text{red}} = 0. \end{cases}$$

$p^\mathcal{E}$ smooth Sobolev extension of p , $u^\mathcal{E} = \nabla p^\mathcal{E}$, $f^\mathcal{E} = -\text{div } u^\mathcal{E}$.

Error estimate for u_h

For $u \in H^m(\Omega)$ with $m \in \{0, \dots, k+1\}$, there holds for $\gamma_{\text{red}} \geq 0$

$$\|\bar{p}_h - \mathcal{E}_h^0 p\|_{L^2(\Omega^T)} + \|u^\mathcal{E} - u_h\|_{\Omega_\gamma} + \gamma_{\text{red}}^{1/2} |u_h|_{\text{red}} \lesssim h^m \|u\|_{H^m(\Omega)} + \|\Pi^Q f^\mathcal{E} - f_h\|_{\Omega^T}.$$

Theorem

For Ω smooth enough to assume L^2 - H^2 regularity, there holds

$$\|\bar{p}_h - \mathcal{E}_h^0 p\|_{L^2(\Omega^T)} \lesssim h \left(\|u_h - u\|_{L^2(\Omega)} + \gamma_{\text{red}}^{1/2} |u|_{\text{red}} \right) + \|f - f_h\|_{-2}$$

Norm on $H(\text{div}, \Omega^{\mathcal{T}})$:

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Theorem

For Ω smooth enough to assume L^2 - H^2 regularity, there holds for the solutions $(u, p) \in H^{\ell+1}(\Omega) \times H^{\ell}(\Omega)$, $f \in H^{\ell+1}(\Omega)$, $0 \leq \ell \leq k$ and $f_h \approx f^{\mathcal{E}}$ well-enough that

$$\begin{aligned} \|u^{\mathcal{E}} - u_h\|_{\Sigma} + \gamma_{\text{red}}^{1/2} |u_h|_{\text{red}} &\lesssim h^{\ell+1} \|u\|_{H^{\ell+1}(\Omega)} + h^{\ell+1} \|f\|_{H^{\ell+1}(\Omega)}, \\ \|\bar{p}_h - \mathcal{E}_h^0 p\|_{L^2(\Omega^{\mathcal{T}})} &\lesssim h^{\ell+2} \|u\|_{H^{\ell+1}(\Omega)} + h^{\ell+2} \|f\|_{H^{\ell+1}(\Omega)}. \end{aligned}$$

Recall the mixed Poisson problem:

$$u - \nabla p = 0 \text{ in } \Omega, \quad \operatorname{div} u = -f \text{ in } \Omega, \quad p = p_D \text{ on } \partial\Omega$$

We solve for $u_h \in \mathbb{RT}^k(\mathcal{T}_h)$, $\bar{p}_h \in \mathbb{P}^k(\mathcal{T}_h)$

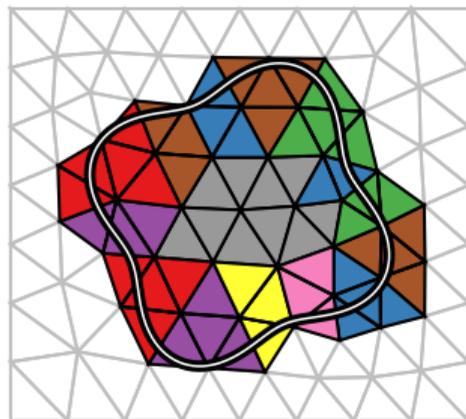
- ▶ We can use the relationship $\nabla p = u$ for a *post-processing* strategy
- ▶ Two goals:
 1. repair the inconsistency: $\bar{p}_h \not\approx p$ on \mathcal{T}_h^Γ
 2. additional order of accuracy for $\bar{p}_h \approx p$

Recall the mixed Poisson problem:

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- ▶ We can use the relationship $\nabla p = u$ for a *post-processing* strategy
- ▶ Two goals:
 1. repair the inconsistency: $\bar{p}_h \not\approx p$ on \mathcal{T}_h^Γ
 2. additional order of accuracy for $\bar{p}_h \approx p$
- ▶ Two versions:
 1. Elementwise
 2. Patchwise



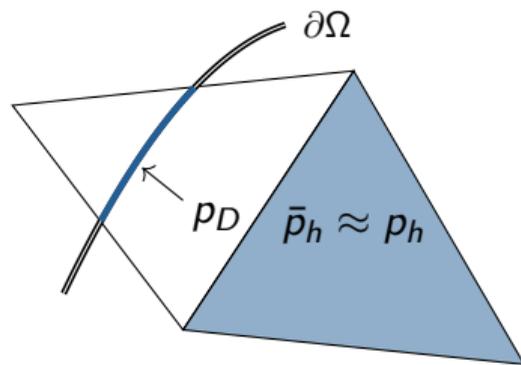
Element-local Scheme

For each $T \in \mathcal{T}_h$, find $p_h^* \in \mathbb{P}^{k+1}(T)$ s.t.

$$(\nabla p_h^*, \nabla q_h^*)_T = (u_h, \nabla q_h^*)_T \quad \forall q_h^* \in \mathbb{P}^{k+1}(T) \setminus \mathbb{R},$$

$$(p_h^*, 1)_T = (\bar{p}_h, 1)_T \quad \text{if } T \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma,$$

$$(p_h^*, 1)_{T \cap \partial\Omega} = (p_D, 1)_{T \cap \partial\Omega} \quad \text{if } T \in \mathcal{T}_h^\Gamma.$$



Error estimate

If $\gamma_{\Omega} > 0$ and $p^\varepsilon \in H^{k+2}(\Omega^\mathcal{T})$, Ω smooth enough s.t. L^2 - H^2 regularity holds, $f \in H^{k+1}(\Omega)$, then

$$\|p^\varepsilon - p_h^*\|_{L^2(\Omega^\mathcal{T})} \lesssim h^{k+2} (\|p\|_{H^{k+2}(\Omega)} + \|f\|_{H^{k+1}(\Omega)}).$$

→ depends on Dirichlet data & requires $\gamma_{\Omega} > 0$

Patchwise Scheme

For each $\omega \in \mathcal{T}_\omega$, find $p_h^* \in \mathbb{P}^{k+1}(\omega)$ s.t. for all $q_h^* \in \mathbb{P}^{k+1}(\omega) \setminus \mathbb{R}$:

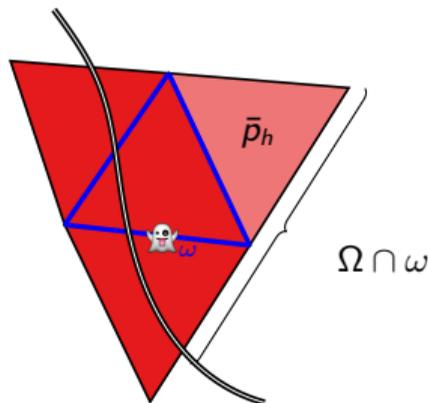
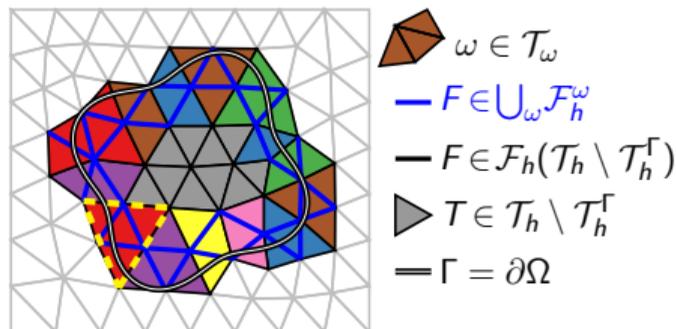
$$\begin{aligned}
 (\nabla p_h^*, \nabla q_h^*)_{\Omega \cap \omega} + \mathfrak{S}_\omega(p_h^*, q_h^*) &= (u_h, \nabla q_h^*)_{\Omega \cap \omega}, \\
 (p_h^*, 1)_{\Omega^{\text{int}} \cap \omega} &= (\bar{p}_h, 1)_{\Omega^{\text{int}} \cap \omega}.
 \end{aligned}$$

Error estimate

For $p \in H^{k+2}(\Omega)$, Ω smooth enough (L^2 - H^2 reg.), $f \in H^{k+1}(\Omega)$, it holds

$$\|p^\mathcal{E} - p_h^*\|_{L^2(\Omega^\mathcal{T})} \lesssim h^{k+2} (\|p\|_{H^{k+2}(\Omega)} + \|f\|_{H^{k+1}(\Omega)}).$$

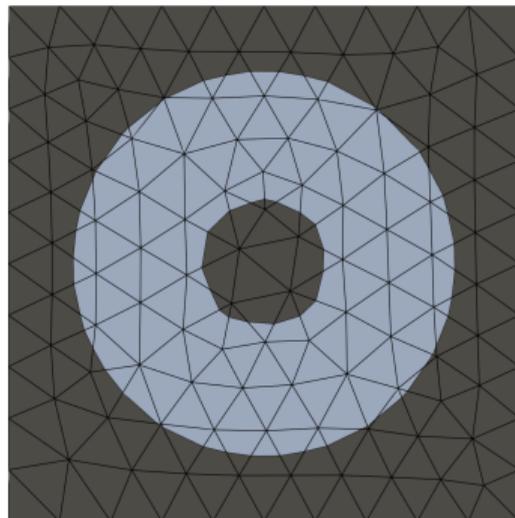
- no dependence on Dirichlet boundary data
- $\gamma_{\mathfrak{S}} = 0$ allowed (hybridization possible)



- ▶ manufactured solution:

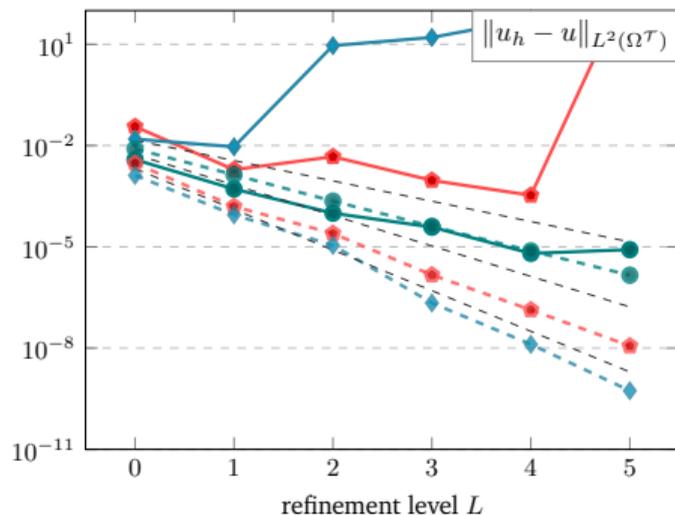
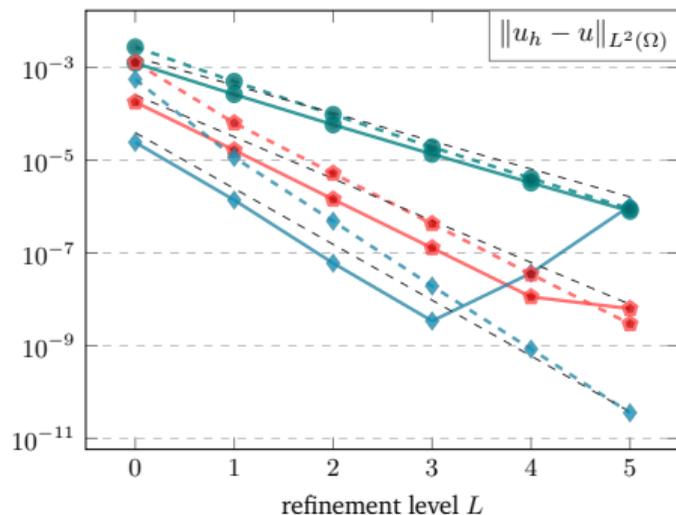
$$p = \sin(x), u = \nabla p, f = -\Delta p$$

- ▶ ring geometry via levelset
- ▶ isoparametric unfitted FEM
- ▶ $\mathbb{RT}^k \times \mathbb{P}^k$, uniform refinements
- ▶ implementation with `ngsxfem`



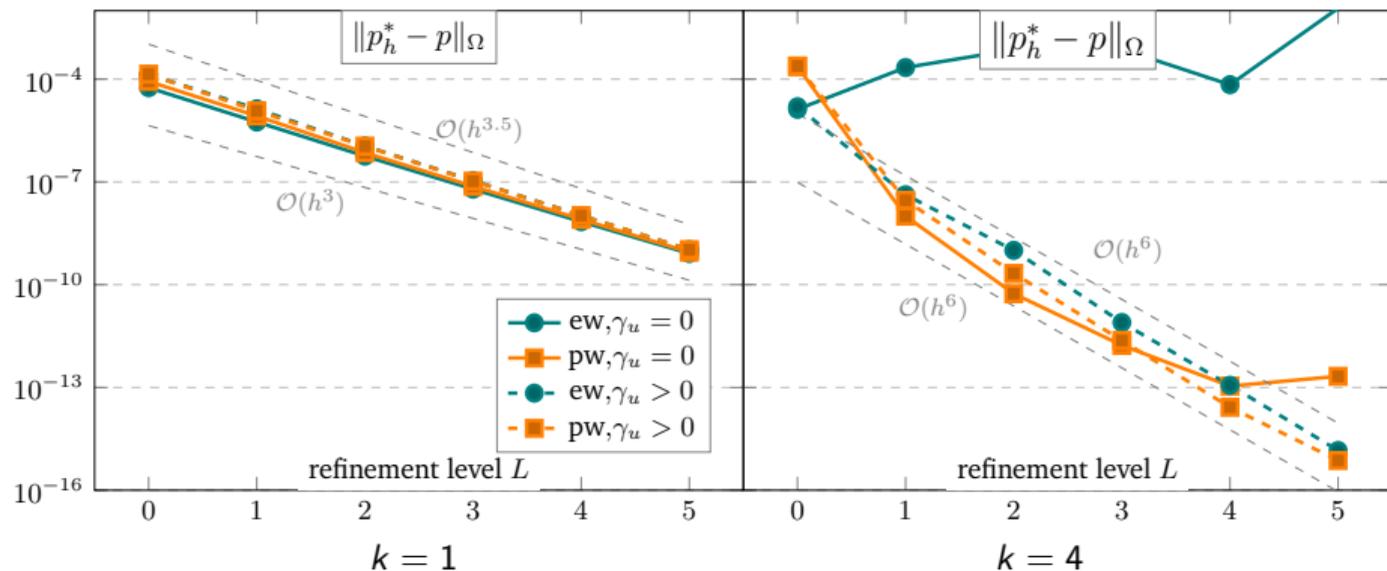
■ C. Lehrenfeld, *High order unf. FEMs on level set doms. using isoparametric mappings*. CMAME, 2016.

■ C. Lehrenfeld, F. Heimann, J. Preuss, H. von Wahl, *ngsxfem: Add-on to NGSolve for geometrically unfitted finite element discretization*. JOSS, 2021.



$\gamma_{\text{robot}} > 0$: dashed, $\gamma_{\text{robot}} = 0$ (solid), $k \in \{1, 2, 3\}$

- ▶ for accuracy on Ω^T , $\gamma_{\text{robot}} > 0$ is necessary
- ▶ for accuracy on Ω , $\gamma_{\text{robot}} = 0$ is possible but conditioning issues possible



- ▶ convergence of order $\mathcal{O}(h^{k+2})$ (as expected)
- ▶ element-wise post-processing requires $\gamma_{\Omega} > 0$

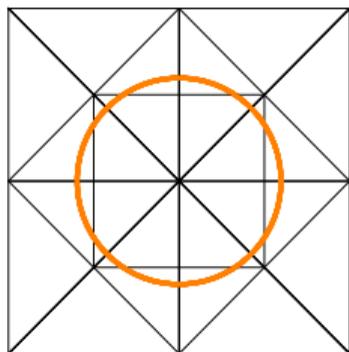
Divergence-preserving unfitted FEM

- ▶ Adding standard γ_{div} -penalty to $(\text{div } u_h, q_h)_{L^2(\Omega)}$ pollutes the mass balance
- ▶ **Extension** from Ω to Ω^T yields inf-sup stability (independent of cut), mass conservation & consistent approx. of u
- ▶ $\bar{p}_h \not\approx p$ on \mathcal{T}_h^Γ , but can be repaired with post-processing:
 - ▶ Elementwise: requires $\gamma_{\text{div}} > 0$ & Dirichlet data;
 - ▶ Patchwise: $\gamma_{\text{div}} = 0$ possible, independent of Dirichlet data
- ▶ $\gamma_{\text{div}} = 0$ possible (\rightarrow hybridization), but conditioning issues possible

Thank you for your attention!

■ C. Lehrenfeld, TvB, I. Voulis, *Analysis of divergence-preserving unfitted finite element methods for the mixed Poisson problem*. Math. Comp., 2025.

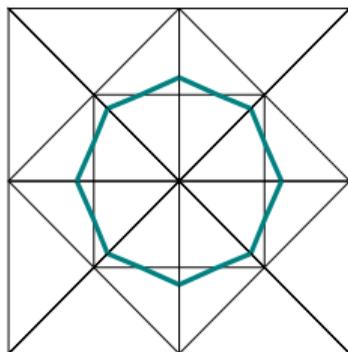




$$\{\phi_h = 0\}$$

implicit, higher order

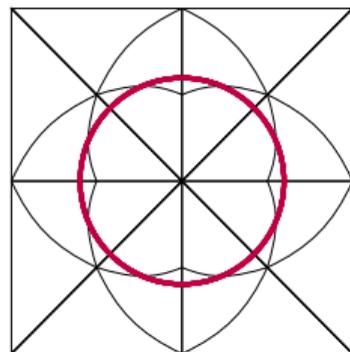
+



$$\{\hat{\phi}_h = 0\}$$

explicit, only 2nd order

$\Theta_h \rightarrow$



$$\Theta_h(\{\hat{\phi}_h = 0\})$$

explicit, higher order

Construct parametric mapping Θ_h of **underlying mesh** such that $\hat{\phi}_h \approx \phi_h \circ \Theta_h$:

$$\rightsquigarrow \text{dist} \left(\Gamma_h, \partial \left(\Theta_h(\Gamma^{\text{lin}}) \right) \right) \leq \mathcal{O}(h^{k_s+1}).$$

Allows to work with $\{\hat{\phi}_h = 0\}$ as **reference and guarantees robust** quadrature.

■ C. Lehrenfeld, *High order unf. FEMs on level set doms. using isoparametric mappings*. CMAME, 2016.

- ▶ Fitted FEM: $f_h = \Pi^Q f = -\Pi^Q \operatorname{div} u = -\operatorname{div} u_h$, but here $-\operatorname{div} u_h = f_h \neq \Pi^Q f^\mathcal{E}$
- ▶ Assumption: f_h approximates $f^\mathcal{E} := -\operatorname{div} u^\mathcal{E}$ well-enough s.t. for $r \in \{0, \dots, k_f + 1\}$, $k_f \in \mathbb{N}$

$$\|f_h - f^\mathcal{E}\|_{L^2(\Omega_T)} + h^{-1} \|f_h - f\|_{-2} \lesssim h^r \|f\|_{H^r(\Omega)},$$

with $\|\cdot\|_{-2} \hat{=}$ operator norm over functionals $H^2(\Omega) \cap H_0^1(\Omega)$.

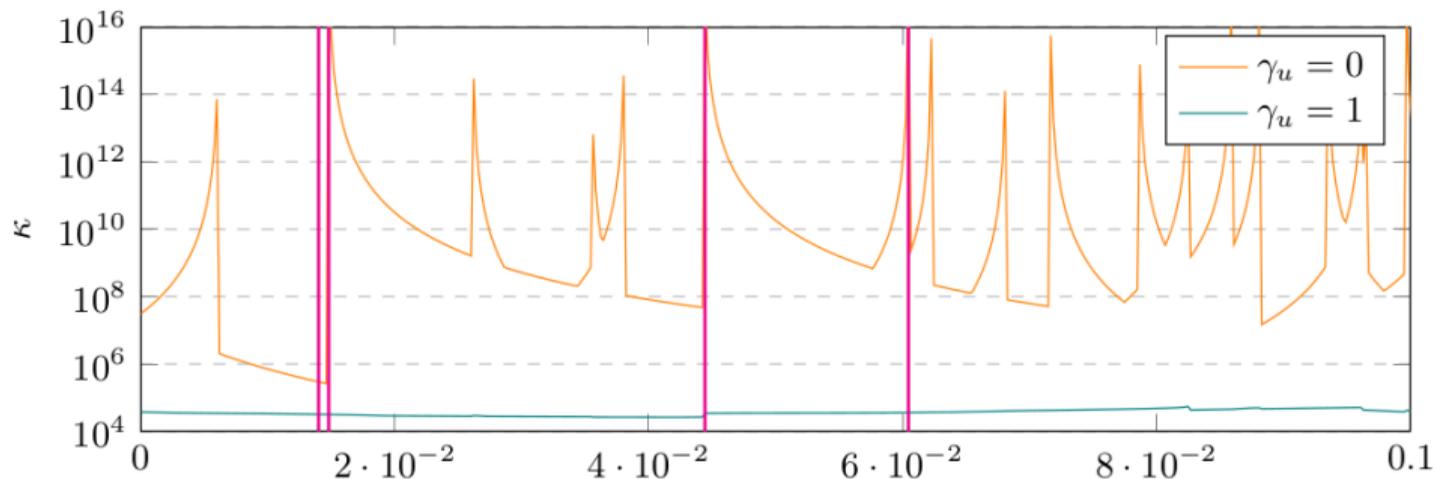
Possible choice of f_h

For $\gamma_f > 0$, find $f_h \in \mathbb{P}^{k_f}(\mathcal{T}_h)$ s.t.

$$(f_h, q_h)_{L^2(\Omega)} + \gamma_f \mathfrak{R}(f_h, q_h) = (f, q_h)_{L^2(\Omega)} \quad \forall q_h \in \mathbb{P}^{k_f}(\mathcal{T}_h).$$

→ fulfills the assumptions from above!

- ▶ analysis requires $k_f \geq k$, but numerics indicate that this could be weakened to $k_f = k - 1$



- ▶ $\gamma_u > 0$ ensures that the condition number is bounded